



# GETRIEBEBAU NORD

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## SK CU4-PNS

Part number: 275 271 014

### PROFIsafe® – Bus interface

The bus interface may only be installed and commissioned by qualified electricians. An electrician is a person who, because of their technical training and experience, has sufficient knowledge with regard to

- Switching on, switching off, isolating, earthing and marking power circuits and devices,
- Proper maintenance and use of protective devices in accordance with defined safety standards.

### DANGER

#### Danger of electric shock

The frequency inverter carries hazardous voltage for up to 5 minutes after being switched off.

- Work must not be carried out unless the frequency inverter has been disconnected from the voltage and at least 5 minutes has elapsed since the mains was switched off.

#### Validity of document

This document is only valid in conjunction with the operating instructions of the respective frequency inverter and the bus communication manual for this bus interface (☞ See overview at end of document). These documents contain all of the information that is required for safe commissioning of the bus interface module and the frequency inverter.

#### Field of use and scope of delivery

The bus interface is used for connecting a NORDAC LINK (SK 260E-FDS or SK 280E-FDS) frequency inverter to a **PROFIsafe** field bus. At the factory, it is installed within the frequency inverter and is not available as an individual part.

The bus interface can directly control up to 3 more frequency inverters via PROFINET IO based on the system bus.

2 secure digital inputs, 2 clock outputs and 2 secure digital outputs are available. Therefore, a maximum of 2 more devices with safe inputs (e.g. frequency inverters, door locks or similar) can be directly controlled via the safe outputs of the bus interface.

The connection of a safety SIN/COS encoder is possible and a prerequisite for the use of the safety functions SLS, SSR, SDI and SOS.

Technical Information / Datasheet	SK CU4-PNS			
PROFIsafe bus interface	TI 275271014	V 1.0	3019	en

## Technical Data

### Applied standards

Standards "functional safety"	EMC standards
EN ISO 13849-1	EN 61800-3-2: 2012
EN 61508 Part 1-7	EN 61800-5-2: 2016

### Bus interface

Firmware (PROFINET)	V2.0 R5	Firmware (PROFIsafe)	V1.4 R0
Supply voltage	24 V + 25 % / - 20 %, ≈ 250 mA reverse polarity protected		

		Key values according to	
		IEC 61508	EN ISO 13849-1
Classification / Basic standards		SIL 3 according to IEC 61508 <sup>1)</sup>	PL e <sup>1)</sup>
Operating mode		"High demand" according to IEC 61508	
Probability of a hazardous failure per hour (PFH value)	SI, SO Sin/Cos encoder, SO	3 x 10 <sup>-9</sup> 1/h 30 x 10 <sup>-9</sup> 1/h	
Operational life		20 years	
Proof Test Interval		20 years	-

<sup>1)</sup>

### Loss of safe function

- An external short circuit between + 24 V and a safe input (SI) is not detected!
- An external short circuit between + 24 V and a safe output (SO) results in the module being switched off with an error message to the fail-safe controller. However, the applied 24 V short circuit is not switched off!

If an exclusion of errors by means of safe wiring is not possible, both the safe input as well as the safe output can be connected with two channels. Dual channel operation must be set by parameterisation.

### Bus specification

PROFIsafe	max. 100 MBaud electrical isolation 500 V <sub>eff</sub>	Cable	min. Ethernet CAT-5
Bus connection	2 x M12	Max. cable length	100 m between two bus interfaces
Bus termination	automatically	Shield	via M12 connection
		Topology	star, tree, ring, line

### Power

Update interval for process data between bus interface and frequency inverter	$\geq 5$ ms
Parameter read access to frequency inverter	$\approx 15$ ms
Parameter write access with saving in EEPROM	$\approx 25$ ms
Cycle times	$\geq 1$ ms

### Additional information for SAFE

Subject	Specification	Unit	min.	Typically	max.
<b>Power supply</b>	Power supply to the module from a safely isolated mains unit	[V]	19.2	24	30
	• 24 V consumption by SK CU4-PNS when idle	[mA]		250	1000
	• Additional requirement for digital outputs and clock outputs (for details, also refer to "Digital outputs")				150
	• Additional requirement for SIN/COS-encoder supply (depends on manufacturer)				
<b>Digital outputs</b>	Low Signal output voltage	[V]		0	0.8
	High Signal output voltage	[V]	17	24	30
	Output current (OSSD 1...3) peak	[mA]		300	500
	$T_{OSSD}$ = Test pulse cycle	[ms]	50	50	50
	$t_{OSSDoff}$ = Pulse length (variable in 200 $\mu$ s steps)	[ms]	0.3	0.5	2.0
	$t_{OSSDon}$ = Pulse pause ( $t_{OSSDoff} \times 2$ )	[ms]	0.8	1.2	4.0
<b>Digital inputs</b>	$t_{OSSDerror}$ = Detection of an OSSD error	[ms]	100	-	150
	$t_{OSSDerror} = T_{OSSD} \times 3$				
	Low Signal input voltage	[V]	-3	0	5
	High Signal input voltage	[V]	15	24	30
	High Signal input current	[mA]			6
	Response time	[ms]			30
<b>Clock outputs</b>	$T_{OSSD}$ = Test pulse cycle(contact test)	[ms]	50		
	$t_{Testoff}$ = Pulse length	[ms]	0.3	0.5	2.0
	Switch-on delay	[ms]	0	0	100
<b>Encoder</b>	Low Signal output voltage	[V]		0	0.8
	High Signal output voltage	[V]	17	24	30
<b>Temperatures</b>	Output current	[mA]			50
	$T_{Takt}$ = Test pulse cycle	[ms]	50		
	$t_{Taktoff}$ = Pulse length	[ms]			2.0
<b>Protection class</b>	Input voltage	[V]		2.25	2.75
	Maximum encoder frequency	[kHz]			150
<b>Ambient temperature</b>	Ambient temperature	[°C]	-25		40
	Storage temperature	[°C]	-25		85
<b>Protection class</b>	Dust-tight and protected against (strong) water jets	IP	55	55	66

### Bus interface characteristics

Communication	RT (Real Time) → Real time communication of process data
	IRT (Isochronous Real Time) → Isochronous real time communication of synchronised process data
Addressing PROFINET IO	Automatic address assignment via IO controller using DCP (Discovery Configuration Protocol)
Data transfer	via Switched Ethernet
Autonegotiation	Negotiation of transfer parameters
Autocrossover	Transmission and receiver cables are automatically crossed in the switch as necessary
Conformity classes	CC-B and CC-C
Access for NORD diagnosis tool via	<ul style="list-style-type: none"> <li>• Diagnostics socket on the device (if available) and via frequency inverter</li> <li>• Ethernet protocols UDP or TCP/IP possible</li> </ul>

Safety communication	Monitoring of process data, sequential numbering of PROFIsafe telegrams (24-bit counter) and checksum test (CRC)
PROFIsafe addressing	F address via DIP - switches

## Connections

The connection for encoder, bus communication and safe inputs and outputs is effected by means of M12 plug connectors at the “connection level” (bottom side) of the frequency inverter.

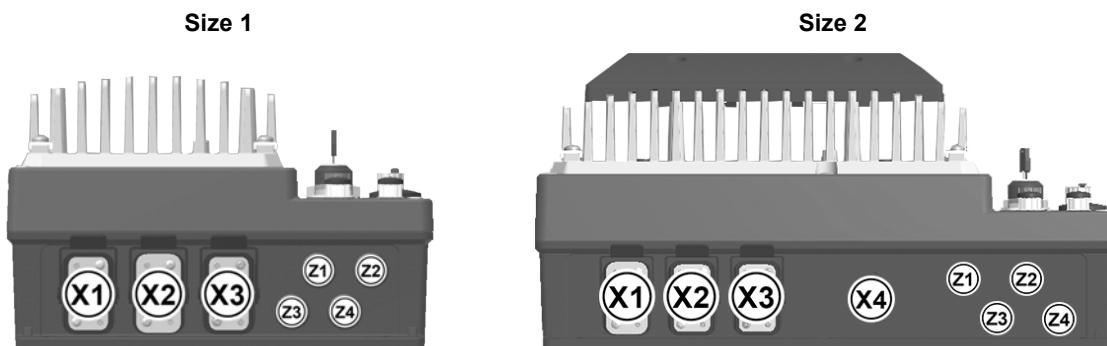
- Industrial Ethernet: PROFINET IO

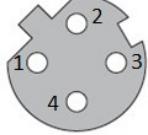
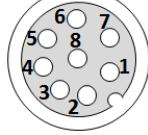
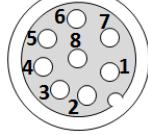
The connection of the two Ethernet cables is effected by means of optional slots Z1 and Z2.

If the bus interface is the last line participant, one of the two M12 connections can remain unassigned.

- Encoder and safe IOs

The connection of a safety SIN/COS encoder and of the safe inputs and outputs is effected by means of optional slots Z3 and Z4.



Function	Plug connector <sup>1)</sup> Contact diagram	Contact assignment								Optional slot	
		1	2	3	4	5	6	7	8		
		No.	Colour								
ETH (Bus-IN)	 Socket, D-coded	TX+	RX+	TX-	RX-					Z1	green
ETH (Bus-OUT)		TX+	RX+	TX-	RX-					Z2	green
SIN-/COS (SIN-/COS encoder)	 Socket, A-coded	0 V	24 V	A	A\	B	B\	-	-	Z3	yellow
SI/SO (safe IOs)	 Socket, A-coded	0 V	24 V	SI1	SI2	SO1	SO2	T1	T2	Z4	yellow

1) The housing of the plug connectors are internally wired to PE.

## Encoder connection

A safety SIN /COS encoder can be connected to implement the safety functions.

### Information

Measurement precision

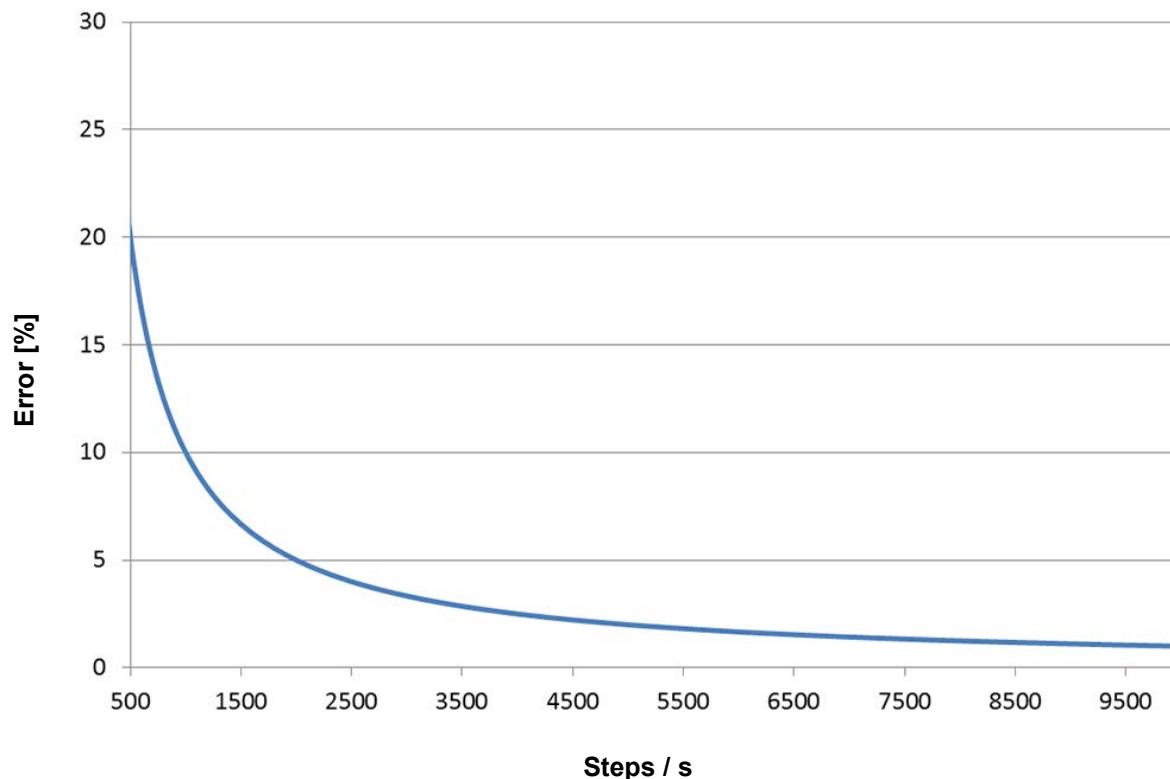
The encoder is evaluated by measuring the frequency. The higher the working frequency which is selected the greater the precision.

To prevent large incorrect measurements, at least 500 measuring steps per second should be selected.

The number of measuring steps per second is calculated from the speed of rotation of the encoder and the selected encoder resolution.

$$inc/s = \frac{\text{RPM} \times \text{Resolution}}{1500}$$

The following diagram shows the percentage measuring error for the set number of steps.



### Information

## Standstill detection

With the use of a single encoder for standstill detection, reduced availability is to be expected under unfavourable EMC conditions. This must be taken into account during planning and compensated for by setting a larger maximum position error.

## Error messages

Error messages from the bus interface can be read out via parameter **P170** of the bus interface (Array [-01] = Actual error, Array [-02] = Previous error).

Error	Meaning	Comments
100.0	EEPROM error	EMC fault, bus interface defective
101.0	System bus 24 V missing	No 24 V voltage on bus, connections not correct
102.0	Bus timeout <b>P151</b>	By means of timeout supervision parameter <b>P151</b>
103.0	System bus Off	No 24 V voltage on bus, connections not correct
550.0	General configuration error	No Ethernet connection (see <b>E10.5</b> )
550.2	Hardware error System bus	EMC fault (see <b>E10.6</b> )
550.3	SAFE hardware error	Error in the safety module (see <b>E10.7</b> )
550.4	FI lost	Connection to system bus participant (FI) lost
550.5	AR lost	PROFINET telegram failure, connection to the IO controller lost (see <b>E10.2</b> )
564.0	MAC address error	MAC address defective

Error messages which occur in relation to the bus interface are depicted as follows in the error memory of the frequency inverter (Parameter **P700** and **P701**).

Error (E010)	Meaning	Comments
10.0	Connection error	<ul style="list-style-type: none"> <li>Contact to bus interface lost</li> </ul>
10.2	PROFINET telegram failure	<ul style="list-style-type: none"> <li>Check physical bus connections</li> <li>Check the status of the PROFINET IO controller</li> </ul>
10.3	Timeout through <b>P151</b>	<ul style="list-style-type: none"> <li>System bus monitoring has triggered.           <ul style="list-style-type: none"> <li>Check time setting parameter <b>P151</b></li> </ul> </li> <li>Telegram transfer is faulty.           <ul style="list-style-type: none"> <li>Reception of cyclic telegrams</li> </ul> </li> <li>Check physical bus connections</li> </ul>
10.5	General PROFINET configuration error	<ul style="list-style-type: none"> <li>Connection to the Ethernet lost.</li> </ul>
10.6	System bus hardware error	<ul style="list-style-type: none"> <li>Remedy EMC fault</li> </ul>
10.7	Hardware error, Safe bus interface	<ul style="list-style-type: none"> <li>An error has occurred in the safe hardware.           <ul style="list-style-type: none"> <li>Remedy EMC fault</li> <li>Restart the bus interface</li> </ul> </li> </ul>
10.8	Timeout connection error	<ul style="list-style-type: none"> <li>Connection between bus interface and frequency inverter interrupted due to timeout.</li> </ul>
10.9	Module missing <b>P120</b>	<ul style="list-style-type: none"> <li>The module entered in parameter <b>P120</b> is not available.</li> </ul>

## PROFIsafe error messages

Error	Meaning	Remarks
5711	Incorrect client address	DIP switch setting or parameterised target address incorrect
5712	Invalid client address	
5713	Invalid host address	Incorrect source address
5714	Watchdog time is zero	A watchdog time of zero is invalid
5715	Incorrect F-SIL	F_SIL level set too high in the controller
5716	Incorrect F-Par version	The F-Par version is not compatible with the bus interface
5717	Incorrect checksum	The checksum for the F-parameter is incorrect
5718	General F parameter error	

Error	Meaning	Remarks
5719	Incorrect i-parameter checksum	Different checksum in controller and bus interface
5721	Different CRC length	
5722	i-parameters have been changed	
5723	Different i-parameter checksum	The checksum and the i-parameter do not match
5724	Incorrect i-parameter checksum	The checksum and the i-parameter do not match
5725	Incorrect F parameter telegram	
5726	Error when reading in DIP switches	DIP switches possibly set to zero
5731	Discrepancy test	Discrepancy at inputs
5732	Diagnostic error at output 1	Short circuit or cross circuit
5733	Diagnostic error at output 2	
5734	Diagnostic error at output 3	
5735	Diagnostic error at clock output 1	
5736	Diagnostic error at clock output 2	
5741	iPar error OSSD1 channel activation	Output activated without activating channel
5742	iPar error OSSD2 channel activation	
5743	iPar error OSSD3 channel activation	
5744	iPar error Clock cycle 1 channel activation	
5745	iPar error Clock cycle 2 channel activation	
5746	iPar error SI1 channel activation	Input activated without activating channel
5747	iPar error SI2 channel activation	
5748	iPar error i parameter channel activation	
5749	iPar error OSSD signal pulse length	
5751	iPar error Digital input filter time	
5752	iPar error Single/dual channel operation	Incorrect setting of parameter <b>P800 I/O operating mode</b>
5753	iPar error Input time discrepancy	Incorrect setting of parameter <b>P803 Discrepancy time</b>
5754	iPar error Passivation	Incorrect setting of parameter <b>P801 Error response</b>
5755	iPar error encoder parameter	Incorrect setting of parameters <b>P810 Encoder</b> , <b>P811 Speed ratio</b> or <b>P813 Encoder resolution</b>
5756	iPar error SLS activation	Incorrect setting of parameter <b>P820</b> and/or <b>P810</b>
5757	iPar error SSR activation	
5758	iPar error SDI-P activation	
5759	iPar error SDI-N activation	
5761	iPar error SOS activation	
5762	iPar error Activation time	Incorrect setting of parameter <b>P821 Activation time</b>
5763	iPar error Response time	Incorrect setting of parameter <b>P822 Response time</b>
5764	iPar error speed	Incorrect setting of parameter <b>P823 Speed</b>
5765	iPar error Tolerance	Incorrect setting of parameter <b>P824 Max. position error</b>
5766	iPar error Limit frequency	Incorrect setting of parameter <b>P811</b> , <b>P812</b> or <b>P823</b>
5771	Temperature outside of specification	Excess temperature (system error)
5772	Encoder safety condition breached	Error at encoder connection (system fault)
5773	SYNC signal not "Low"	Bus interface synchronisation error (system error)
5774	Supply voltage error	The supply voltage is too high or too low
5775	Supply voltage error	The supply voltage is too high or too low
5776	Speed difference error	The difference between the speeds measured by the two processors is too high
5781	SLS error	The set SLS speed has been exceeded
5782	SSR error	The set SSR speed has been exceeded or undershot
5783	SDI_P error	The encoder has detected a negative direction
5784	SDI_N error	The encoder has detected a positive direction
5785	SOS error	Number of values counted by the encoder larger than the set tolerance
5791	System error saved in flash memory	The triggered system error is saved
5792	Maximum number of system errors	More than 15 system errors have occurred (replace bus interface)
5797	Flash memory access error	Flash memory access error cannot be saved

## Parameters

**Frequency inverter:** The following frequency inverter parameters must be adapted for setting up communication between the frequency inverter and the bus interface (for details please refer to the frequency inverter manual).

Parameter [-Array]	Meaning	Remarks
P120 [-01]	Option monitoring	"Auto" (default setting)
P509	Source Control Word	"System bus"
P510 [-01]...[-02]	Setpoint source	"Auto" (default setting)
P543 [-01]...[-03]	Bus actual value (1...3)	Possible settings according to P418
P546 [-01]...[-03]	Bus setpoint value (1...3)	Possible settings according to P400
P700 [-01]/P701	Current/last faults	Information parameter
P740/P741	Process data bus In / Out	Information parameter
P748	CANopen/System bus status	Information parameter

**Bus interface:** The bus interface provides a selection of appropriate parameters for setting or displaying special operating values. Parameters can be adapted using the NORDCON software or an SK PAR-3H / -3E parameter box. All parameters can still be read from and written to by the bus master via PROFINET IO.

Parameter [-Array]	Meaning	Remarks	-TU3-	-TU4-	-CU4-
P150	Set relays	Set DOUT directly or control via bus		X	
P151	External bus time-out	Monitoring of SK xU4 bus interface		X	X
P152	Factory setting	Reset bus interface parameters	X	X	X
P153 [-01 ...]	Minimum system bus cycle	Reduction of bus load on the system bus caused by the bus interface		X	X
P154 [-01 ...]	Access to option card I/O	Administration of read and write permissions to the IOs of the bus interface		X	X
P160 [-01...]	IP address		X	X	X
P161 [-01...]	IP subnet mask		X	X	X
P162	Device name	Up to 240 characters (ASCII codes 45 ... 122), save by entering "0" as the final character	X	X	X
P163 [-01 ...]	Alarm test	Sets a diagnostic alarm	X	X	X
P164 [-01 ...]	IP Gateway	IP-Address for Gateway functionality	X	X	X
P170 [-01 ...]	Present errors	Indication of a bus interface error	X	X	X
P171 [-01 ...]	Software version	Firmware version/Revision	X	X	X
P172	Configuration	Bus interface type	X	X	X
P173 [-01 ...]	Module status	Status of system bus or the connected FI	X	X	X
P174	Status of digital inputs	Image of the switching status of DIN		X	X
P175	Digital output state	Image of the switching status of DOUT		X	
P176 [-01...]	Process data bus In	Information parameter	X	X	X
P177 [-01...]	Process data bus Out	Information parameter	X	X	X
P178	Internal temperature	Information parameter			X
P180 [-01 ...]	PPO Type	Information parameter	X	X	X
P181 [-01 ...]	MAC address	Information parameter	X	X	X
P185 [-01 ...]	Present IP address	Information parameter	X	X	X
P186 [-01 ...]	Current IP subnet mask	Information parameter	X	X	X
P187 [-01 ...]	Actual IP Gateway	Information parameter	X	X	X
P190	Status DIP-switches	Information parameter	X	X	X

## Additional parameters for PROFIsafe

Parameter [-Array]	Meaning	Remarks	-TU4-	-CU4-
P800 [-01...]	I/O operating mode	Digital input/output operating mode: single or dual channel	X	X
P801	Error response	Safe output response to an error	X	X
P802 [-01...]	Channel activation	Activate inputs and outputs	X	X
P803	Discrepancy time	Permissible time difference for dual channel mode (→P800)	X	X
P804	OSSD pulse	Pulse width for testing outputs	X	X
P805	Filter time	Filter time for digital inputs SI1 and SI2	X	X
P810	Encoders	Activate encoder evaluation	X	X
P811	Speed ratio	Set speed ratio "motor speed/encoder speed" (→P810)	X	X
P812	Encoder resolution	Set encoder resolution	X	X
P820 [-01...]	Safety function	Switch safety functions On/Off	X	X
P821 [-01...]	Activation time	Safety function activation time (→P820)	X	X
P822 [-01...]	Response time	Reaction time of safety function (→P820) to an error	X	X
P823 [-01...]	Speed limit	Set the speed limit for safety functions (→P820)	X	X
P824 [-01...]	Max. position error	Set maximum position deviation for safety function	X	X
P830	Save I parameter	Save settings P800...P824 in flash memory	X	X
P840	I-parameter CRC	Display i parameter checksum (CRC)	X	X
P841	Actual error	Display of the actual error present	X	X
P842	Last error	Display last error	X	X
P843	Software version	Display software version	X	X
P844 [-01...]	Temperature	Display actual temperature of bus interface	X	X
P845 [-01...]	Actual voltage	Display actual voltage of bus interface	X	X
P846 [-01...]	Status of DIP switches	Display DIP - switch settings	X	X
P847	Speed	Display the speed measured by the encoder	X	X
P848 [-01...]	System error	Display system errors (incl. total number of errors)	X	X

## Parameter access and diagnosis

The access to the parameters of the bus interface is effected exclusively by means of the frequency inverter's diagnostics socket.

Further documentations and software ([www.nord.com](http://www.nord.com))

Software	Description	Software	Description
<a href="#">GSDML-file</a>	Device characteristics and parameters	<a href="#">NORDCON</a>	Parametrisation and diagnostic software
Document		Document	
<a href="#">BU 0000</a>	Description of NORDCON software		<a href="#">BU 2800</a>
<a href="#">BU 0040</a>	Parameter box manual		<a href="#">BU 0250</a>