

SK TU4-ECT-C

Part number: 275 281 167

EtherCAT® – External Bus Interface

The bus interface may only be installed and commissioned by qualified electricians. An electrician is a person who, because of their technical training and experience, has sufficient knowledge with regard to

- Switching on, switching off, isolating, earthing and marking power circuits and devices,
- Proper maintenance and use of protective devices in accordance with defined safety standards.



DANGER

Danger of electric shock

The frequency inverter carries hazardous voltage for up to 5 minutes after being switched off.

- Work must not be carried out unless the frequency inverter has been disconnected from the voltage and at least 5 minutes has elapsed since the mains was switched off!

NOTICE

Validity of document

This document is only valid in conjunction with the operating instructions of the respective frequency inverter and the bus communication manual for this bus interface (📖 See overview at end of document). These documents contain all of the information that is required for safe commissioning of the bus interface module and the frequency inverter.

Scope of delivery

| | | |
|------------------------------|-------------------------------------|--|
| 1 x | Bus interface | SK TU4-ECT-C |
| 4 x | Hexagonal socket screw | M4 x 40 mm |
| <i>Accessories required:</i> | | |
| 1 x | Bus connection unit TI 275280500 | SK TI4-TU-BUS-C (Part No.: 275 280 500) |



Usage area

External technology unit for connecting a decentralised frequency inverter (SK 180E...SK 2xxE) to an **EtherCAT** field bus. The bus interface can be mounted on, or in the immediate vicinity of the frequency inverter. This is connected to the inverter via the system bus, and can directly access up to 4 frequency inverters. 8 digital inputs and 2 digital outputs are available.

| Technical Information / Datasheet | SK TU4-ECT-C | | | |
|-----------------------------------|--------------|-------|------|----|
| EtherCAT Bus module | TI 275281167 | V 1.5 | 4217 | en |

Technical Data

Bus interface

| | |
|-------------------|---|
| Temperature range | -25 °C ... 50 °C |
| Temperature class | Class 3K4 |
| Protection class | IP66 |
| Supply voltage | 24 V ± 20 %, ≈ 100 mA Reverse polarity protected |

| | |
|----------------------|-----------------------------|
| Vibration resistance | 3M7 |
| Firmware version | V1.8 R0 |
| Hardware version | BB |
| Dimensions [mm]* | H x W x D: 95 x 136 x 99 |

*bus interface fitted to bus connection unit
Depth: 108 mm with cover caps on M12 connection

| | |
|--------------------------------------|---|
| Digital input - working range | Low: 0 V ... 5 V, High: 15 V ... 30 V |
| Digital input - specific data | $R_i = 8 \text{ k}\Omega$, input capacity: 10nF, sampling rate 1 ms, reaction time 1 ms, inputs according to EN 61131-2 type 1 |
| Digital output - 24 VDC power supply | ≤ 400 mA (input) |
| Digital output - working range | Low = 0 V, High = 24 V; max. 200 mA |

Bus specification

| | |
|-----------------|---|
| EtherCAT | max. 100 MBaud |
| | electrical isolation 500 V _{eff} |
| Bus connection | 2 x M12 sockets |
| Bus termination | performed automatically |
| Status display | 6 LEDs |
| Topology | Linear bus |
| Process data | 8 bytes per FI + 2 bytes for IOs Total length 2 ... 34 Bytes |

| | |
|-------------------|----------------------------------|
| Cable | Min. Ethernet CAT-5 |
| Max. cable length | 100 m between two bus interfaces |
| Shield | via M12 direct to PE |
| PE connection | via PE screw cap in terminal box |
| | |
| | |

Power

| | |
|---|----------|
| Update interval of process data for 1000 devices | ≈ 1 ms |
| Update interval for process data between bus interface and frequency inverter | ≈ 1.5 ms |
| Parameter read access on the frequency inverter | ≈ 15 ms |
| Parameter write access with storage in EEPROM | ≈ 25 ms |

Bus interface characteristics

| | |
|--------------------------------------|--|
| Parametrisation | via CoE (CANopen over EtherCat) |
| Error Messages (Emergency Messages) | in acc. with CANopen DS-301 |
| EtherCAT Addressing (Second Address) | DIP switch or bus interface parameters |
| Distributed Clocks | not supported |
| Access for NORD diagnosis tool via | diagnosis socket on the device (if available) and via frequency inverter |

Installation

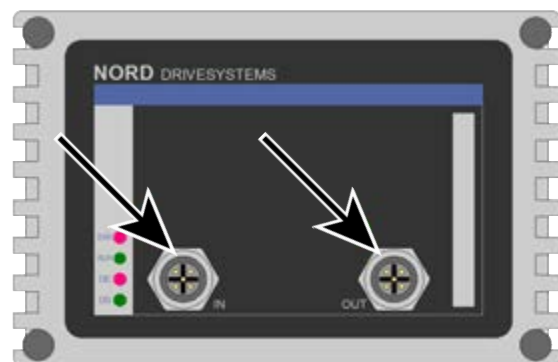
The bus interface must be attached to a suitable connection unit (SK TI4-TU...) and connected using the 4 provided M4 x 40 mm hexagon socket collar screws. Installation details can be found in the data sheet for the relevant connection units.

Connections

The two Ethernet lines are connected exclusively via the two M12 sockets on the front. If the bus interface is the final subscriber on the line, one M12 socket can remain unoccupied. The use of EMC cable glands is recommended.

| PIN | Signal | Description |
|-----|--------|---------------------|
| 1 | TX+ | Transmission Data + |
| 2 | RX+ | Receive Data + |
| 3 | TX- | Transmission Data - |
| 4 | RX- | Receive Data - |

PIN assignment
M12-4 socket
("D"- coded)



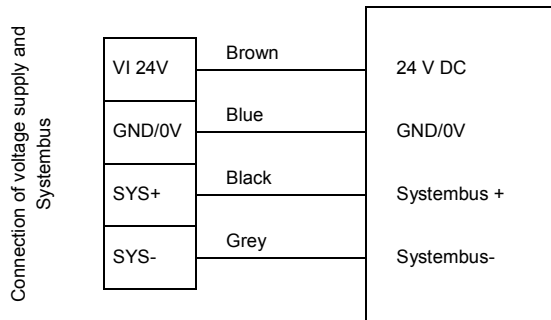
The connection to other signal and control lines takes place via the bus connection unit **SK TI4-TU-BUS(-C)**.

| | | |
|---------------------|----------------------------|---|
| Terminals | Double-sprung terminal bar | 2 x 18 contacts |
| Cable cross section | AWG 14-26 | rigid: 0,14 ... 2,5 mm flexible: 0.14 ... 1.5 mm with wire end sleeves |
| PE connection | Via housing | |
| RJ12 | RJ45 - socket | Interface for connecting a parameterisation tool |

| Potential | Contact | Designation | Description | |
|-----------|-------------------------------------|-------------|-------------|--|
| 1 | Digital inputs | 1 | 24 V | Supply potential (+24 V, ≤ 200 mA) |
| | | 2 | 24 V | Supply potential (+24 V, ≤ 200 mA) |
| | | 3 | DIN5 | Digital input 5 |
| | | 4 | DIN7 | Digital input 7 |
| | | 5 | DIN6 | Digital input 6 |
| | | 6 | DIN8 | Digital input 8 |
| | | 7 | 0 V | Reference potential (0 V / GND) |
| | | 8 | 0 V | Reference potential (0 V / GND) |
| | | 9 | 24 V | Supply potential (+24 V, ≤ 200 mA) |
| | | 10 | 24 V | Supply potential (+24 V, ≤ 200 mA) |
| 2 | System bus level and digital inputs | 11 | 24 V | Supply voltage (+24 V) |
| | | 12 | 24 V | Supply voltage (+24 V) |
| | | 13 | 24 V | Supply voltage (+24 V) |
| | | 14 | SYS + | System bus data line + |
| | | 15 | 0 V | Reference potential (0 V / GND) |
| | | 16 | SYS - | System bus data line - |
| | | 17 | 0 V | Reference potential (0 V / GND) |
| | | 18 | 0 V | Reference potential (0 V / GND) |
| | | 19 | DIN1 | Digital input 1 |
| | | 20 | DIN3 | Digital input 3 |
| | | 21 | 0 V | Reference potential (0 V / GND) |
| | | 22 | 0 V | Reference potential (0 V / GND) |
| | | 23 | 24 V | Supply voltage (+24 V) |
| | | 24 | 24 V | Supply voltage (+24 V) |
| | | 25 | DIN2 | Digital input 2 |
| | | 26 | DIN4 | Digital input 4 |
| | | 27 | 0 V | Reference potential (0 V / GND) |
| | | 28 | 0 V | Reference potential (0 V / GND) |
| | | 29 | 24 V | Supply voltage (+24 V) |
| | | 30 | 24 V | Supply voltage (+24 V) |
| 3 | Digital outputs | 31 | VI 24V2 | Supply potential (+24 V - in) of the digital outputs |
| | | 32 | 0V2 | Reference potential (0 V / GND) of the digital outputs |
| | | 33 | DOUT1 | Digital output 1 (+24 V, ≤ 200 mA) |
| | | 34 | DOUT2 | Digital output 2 (+24 V, ≤ 200 mA) |
| | | 35 | 0V2 | Reference potential (0 V / GND) of the digital outputs |
| | | 36 | 0V2 | Reference potential (0 V / GND) of the digital outputs |
| 4 | Diagnosis | RJ12 - 1 | RS485_A | Data cable RS485 |
| | | RJ12 - 2 | RS485_B | Data cable RS485 |
| | | RJ12 - 3 | GND | Reference potential (GND) |
| | | RJ12 - 4 | RS232_TxD | Data cable RS232 |
| | | RJ12 - 5 | RS232_RxD | Data cable RS232 |
| | | RJ12 - 6 | 24 V | Supply voltage (+24 V) |



Connection examples



bus module

Configuration

No settings need to be made on the device. However, the bus interface can be configured with a fixed address because of the "Hot Connection Group" functionality, the so-called "Second Address". This takes place using the DIP switches of the bus interface. The DIP switch settings are read after a "Power On" of the bus interface.

| DIP switch | | | | | | | | | | | Meaning | |
|--------------------------------------|----|----|---|---|---|---|---|---|---|---|---------|---|
| 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | Address |
| X | X | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | X | 0 |
| X | X | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | X | 1 |
| X | X | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | X | 2 |
| X | X | - | - | - | - | - | - | - | - | - | X | - |
| X | X | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | X | 511 |
| | | | | | | | | | | | 0 | System bus terminating resistor not set. |
| | | | | | | | | | | | 1 | System bus terminating resistor set. |
| Access rights for remote maintenance | | | | | | | | | | | | |
| | | 0 | | | | | | | | | | Only read access to parameters possible. |
| | | 1 | | | | | | | | | | Read and write access to parameters possible. |
| 0 | | | | | | | | | | | | No control possible. |
| 1 | | | | | | | | | | | | Control is possible. |

1. System bus (DIP 1)

The system bus must be terminated at both physical ends.

2. Second Address (DIP 2...10)

The „Second Address“ can be set via this switch and controlled in parameter **P181**.

If all DIP switches 2...10 are moved to the "OFF" position, the „Second Address“ can be set via parameter **P160**.

3. Access rights for remote maintenance (DIP 11...12)

The bus interface and the connected frequency inverter can be accessed via remote maintenance using the TCP Ethernet protocol. The type of access is defined via the DIP switch with inputs 10 to 11.



Factory settings DIP switches: **OFF**

LED indicators

The operating statuses of the bus interface are visualised using LED indicators.

| No. | Name | Colour | Meaning |
|-----|----------|--------|----------------|
| 1 | RUN | green | Ethernet State |
| | ERR | red | Ethernet Error |
| | DS | green | Device State |
| | EN | red | Device error |
| 2 | Link/Act | green | Link/Activity |



EtherCAT-specific LED

| RUN | State | Meaning |
|--------------|------------------|--|
| OFF | Init | <ul style="list-style-type: none"> No communication of process data and parameters |
| Flashing | Pre-Operational | <ul style="list-style-type: none"> Parameter communication active No process data communication |
| Single Flash | Save Operational | <ul style="list-style-type: none"> Parameter communication active Restricted process data communication No restrictions to actual values Setpoints not evaluated |
| ON | Operational | <ul style="list-style-type: none"> Parameter communication active Unrestricted process data communication |

| ERR | State | Meaning |
|--------------|------------------------------|---|
| OFF | No Error | <ul style="list-style-type: none"> EtherCAT functioning normally on the bus interface |
| Flashing | Invalid Configuration | <ul style="list-style-type: none"> General EtherCAT configuration error, may be generated because of an erroneous XML file |
| Single Flash | Unsolicited State Change | <ul style="list-style-type: none"> Bus interface has changed the EtherCAT state without authorisation |
| Double Flash | Application Watchdog Timeout | <ul style="list-style-type: none"> EtherCAT or FI timeout (P513 or P151) |

| L/A (Green LED) | State | Meaning |
|-----------------|---------------|--|
| OFF | No Connection | <ul style="list-style-type: none"> Bus interface not ready, no control voltage, No bus connection (check cable connection) |
| Flashing | Active | <ul style="list-style-type: none"> Bus interface connected and active |
| ON | Inactive | <ul style="list-style-type: none"> Bus interface ready for operation, but no bus activity present |

NORD-specific LEDs

| DS (Device State) | EN (Device Error) | Meaning long flashing = 0.5 s on / 1 s off short flashing = 0.25 s on / 1 s off |
|----------------------|--|--|
| OFF | OFF | Bus interface not ready, no control voltage |
| ON | OFF | Bus interface ready, no error, at least one frequency inverter is communicating via the system bus |
| ON | Short flashing | Bus interface ready, but <ul style="list-style-type: none"> One or more of the connected frequency inverters has fault status |
| Long flashing | OFF | Bus interface ready and at least one other subscriber is connected to the system bus, but <ul style="list-style-type: none"> No frequency inverter on the system bus (or connection interrupted) One or more system bus subscriber has an address error Software incompatible (bus interface software and FI software incompatible - update required) |
| Long flashing | Short flashing Flash interval 1 x - 1s pause | System bus is in status "Bus Warning" <ul style="list-style-type: none"> Communication on system bus disrupted No other subscribers present on system bus Module not inserted correctly or no connection to system bus Frequency inverter has no supply voltage |
| Long flashing | Short flashing Flash interval 2 x - 1s pause | System bus is in status "Bus Off" <ul style="list-style-type: none"> The system bus 24 V power supply has been interrupted during operation |
| Long flashing | Short flashing Flash interval 3 x - 1s pause | System bus is in status "Bus Off" <ul style="list-style-type: none"> The 24V voltage supply of the system bus is missing |
| Long flashing | Short flashing Flash interval 4 x - 1s pause | Bus interface error <ul style="list-style-type: none"> See parameter P170 |
| OFF | Short flashing Flash interval 1...7 - 1s pause | System error, internal program sequence interrupted <ul style="list-style-type: none"> EMC interference (observe the wiring guidelines!) Bus interface defective |

Error messages

Error messages from the bus interface - current or archived message relating to the last fault - can be read out via bus interface parameter **P170**. The error messages are lost if the bus interface is switched off.

| Error | Meaning | Remarks |
|--------------------|-----------------------------------|--|
| 100.0 | EEPROM error | EMC faults, bus interface defective |
| 102.0 | Timeout | via P151/P513 monitoring |
| 103.0 | System bus BUS OFF | No 24 V supply to the bus, connections not correct |
| 104.0 | Bus interface temperature > 91 °C | only SK CU4-..., permissible internal temperature of the bus interface exceeded for approx. 60 sec |
| 550.1 | DIP switch error | The DIP switches (IP address) could not be read correctly |
| 560.0 ... 560.9 | Internal error | Bus interface not ready |
| 561.0 | General network error | |
| 561.1 | Ethernet Watchdog timeout | |
| 561.2 | Bus cable fault | Bus cable connection interrupted |
| 561.3 | IP address error | IP address of bus interface has been doubly assigned |
| 563.0 | Firmware version incompatible | The firmware version cannot be used for the device |
| 564.0 | MAC address defective | |

Errors which occur in relation to the bus interface are depicted as follows in the error memory of the frequency inverter (P700 / P701).

| Error (E010) | Meaning | Remarks |
|--------------|---|---|
| 10.0 | Connection error | Contact to SK xU4 lost |
| 10.1 | ASIC error | Communication with Ethernet ASIC lost <ul style="list-style-type: none"> • Supply voltage shut-off • Reduce temperature of bus interface to less than 91 °C (SK CU4-... only) |
| 10.2 | Ethernet Watchdog timeout | Telegram transfer error <ul style="list-style-type: none"> • Check the connections and links, program sequence and Bus Master |
| 10.3 | Timeout by P151/P513 | Telegram transfer error <ul style="list-style-type: none"> • Check the connections and links • Check the Watchdog time |
| 10.4 | IP address error | IP address of bus interface has been doubly assigned |
| 10.5 | Internal error | Module not ready for operation, configuration error |
| 10.6 | Bus cable fault | Bus cable connection interrupted |
| 10.8 | The connection between inverter and bus interface had timeout | SK TU3 bus interface only |
| 10.9 | Bus interface missing (P120) | SK xU4 bus interface only |

Parameters

Frequency inverter: The following frequency inverter parameters must be adapted for setting up communication between the frequency inverter and the bus interface (for details please refer to the frequency inverter manual).




| Parameter [-Array] | Meaning | Remarks | |
|--|-----------------------------------|--|--------------|
| P120 [-01] | Option monitoring | "Auto" (default setting) | Only SK xU4 |
| P509 | Source Control Word | SK TU3-... on SK 5xxE: "Ethernet TU" SK xU4-... on SK 180/SK 2xxE: "System bus" | |
| P510 [-01]...[-02] | Setpoint source | "Auto" (default setting) | |
| P513 | Time-out | Monitoring of the SK TU3 bus interface | Only SK 5xxE |
| P543 [-01]...[-03] ([-05]) and P543...P545 | Bus actual value (1...3 (...5)) | Possible settings according to P418 | |
| P546 [-01]...[-03] ([-05]) and P546...P548 | Bus setpoint value (1...3 (...5)) | Possible settings according to P400 | |
| P700 [-01]/P701 | Current/last faults | Information parameter | |
| P740/P741 | Process data bus In / Out | Information parameter | |
| P745 | Module version | Information parameter | Only SK TU3 |
| P746 | Module status | Information parameter | Only SK TU3 |
| P748 | CANopen/System bus status | Information parameter | |

Bus interface: The bus interface provides a selection of appropriate parameters for setting or displaying special operating values. Parameters can be adapted using the NORDCON software or an SK PAR-3H / -3E parameter box. All parameters can still be read from and written to by the bus master via EtherCAT.

| Parameter [-Array] | Meaning | Remarks | -TU3- | -TU4- | -CU4- |
|--------------------|---------------------------|---|-------|-------|-------|
| P150 | Set relays | Set DOUT directly or control via bus | | X | |
| P151 | External bus time-out | Monitoring of SK xU4 bus interface | | X | X |
| P152 | Factory setting | Reset bus interface parameters | X | X | X |
| P153 [-01 ... -02] | Minimum system bus cycle | Reduction of bus load on the system bus caused by the bus interface (SK xU4 only) | | X | X |
| P154 [-01 ... -02] | Access to option card I/O | Administration of read and write permissions to the IOs of the bus interface | | X | X |
| P170 [-01 ... -02] | Present errors | Display bus interface errors | X | X | X |
| P171 [-01 ... -03] | Software version | Firmware version/Revision | X | X | X |
| P172 | Configuration | Bus interface type | X | X | X |
| P173 | Module status | Status of system bus or connected FC | X | X | X |
| P174 | Status of digital inputs | Image of the switching status of DIN | | X | X |
| P175 | Digital output state | Image of the switching status of DOUT | | X | |
| P176 [-01...] | Process data bus In | Information parameter | X | X | X |
| P177 [-01...] | Process data bus Out | Information parameter | X | X | X |
| P178 | Internal temperature | Information parameter | | | X |
| P180 | NMT State | Information parameter | X | X | X |
| P181 | Second Address | Information parameter | X | X | X |
| P182 | EtherCat Watchdog | Watchdog Supervision Time | X | X | X |
| P183 [-01...-04] | EtherCAT transfer error | Transmission error at EtherCAT level | X | X | X |
| P184 | SPI error counter | Information parameter | X | X | X |

Parameter access and diagnostics

The NORD CON software and optional control units such as the SK PAR-3H parameter box provide convenient access to the parameters of the bus interface and allow status information to be read out.

| SK TU3- | SK TU4- | SK CU4- / SK TU4- |
|--|---|---|
| Access via RJ12 diagnostics socket of the SK 5xxE  | Access via RJ12 diagnostics socket of the bus connection unit SK TI4-TU-BUS(-C)  | Access via RJ12 frequency inverter diagnostics socket, if connected to the bus interface via the system bus.  |

Further documentation and software (www.nord.com)

| Software | Description |
|--------------------------|---------------------------------------|
| XML-file | Device characteristics and parameters |

| Software | Description |
|--------------------------|---|
| NORD CON | Parametrisation and diagnostic software |

| Document | Description |
|-------------------------|--|
| BU 0000 | Description of NORD CON software |
| BU 0040 | Parameter box manual |
| BU 0180 | Frequency inverter manual SK 180E, SK 190E |
| BU 0200 | Frequency inverter manual SK 2xxE |

| Document | Description |
|------------------------------|---|
| BU 2300 | EtherCAT bus communication manual |
| TI 275280500 | Bus connection unit SK TI4-TU-BUS-C |
| TI 275274505 | SK TIE4-M12-SYSM System bus connection expansion exit |
| TI 275274506 | SK TIE4-M12-SYSS System bus connection expansion entrance |